

# Integration by parts for pinned point processes

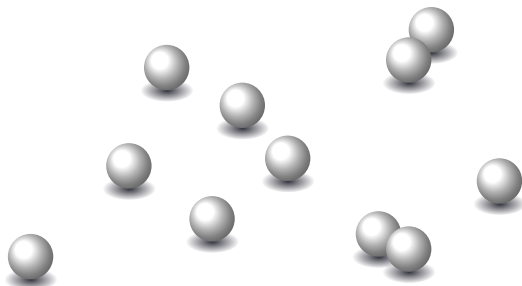
Mathias Rafler  
Justus-Liebig-Universität Gießen

Stochastic and Analytic Methods in Mathematical Physics  
Yerevan, September 2–7, 2019

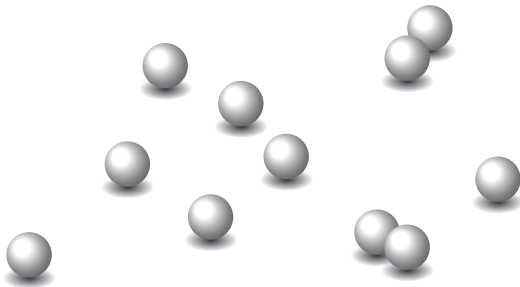
# Plan of the talk

- ① How to describe point processes
- ② Pinning and examples
- ③ Characterization
- ④ Key steps
- ⑤ Remarks on further examples

# How to describe point processes

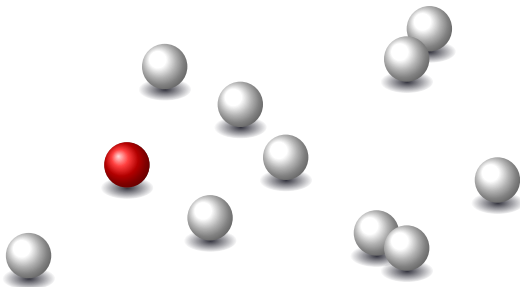


## How to describe point processes

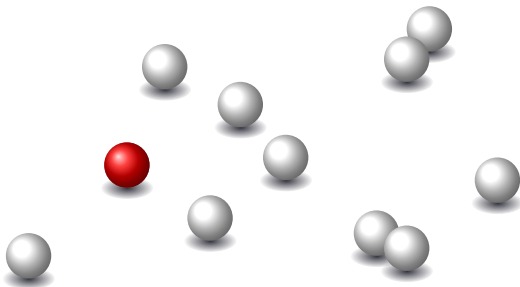


static: total number of points and joint law

# How to describe point processes

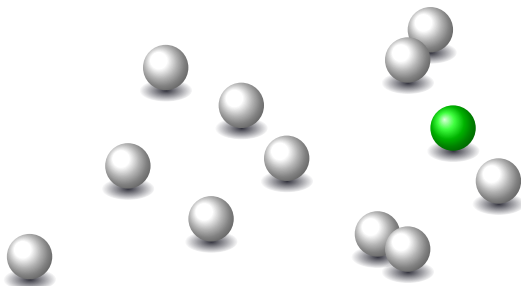


## How to describe point processes

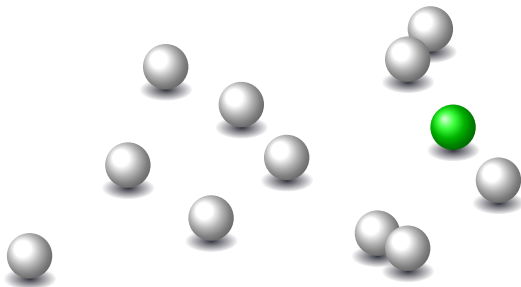


dynamic: how to remove

# How to describe point processes



# How to describe point processes



dynamic: how to add

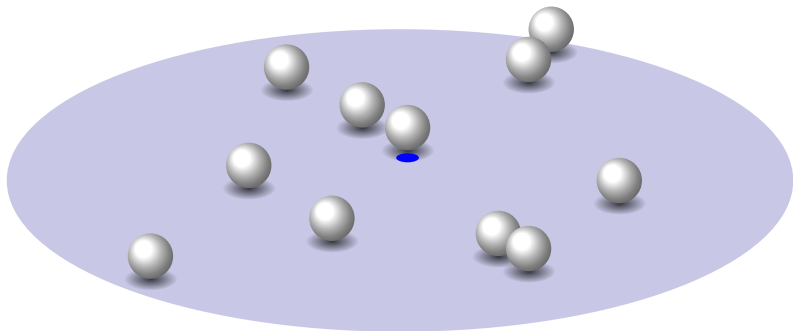


# How to describe point processes

- ▶ dynamics for Markov process (existence different story)
  - ▶ **add** – birth
  - ▶ **remove** – death
- ▶ existence and uniqueness of stationary/reversible distribution

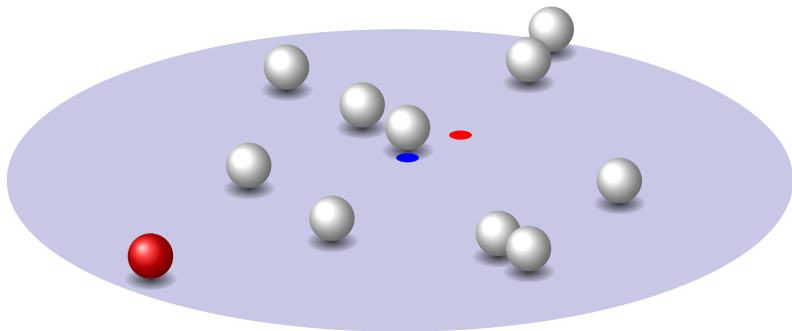
# Pinning a point process

Barycentre



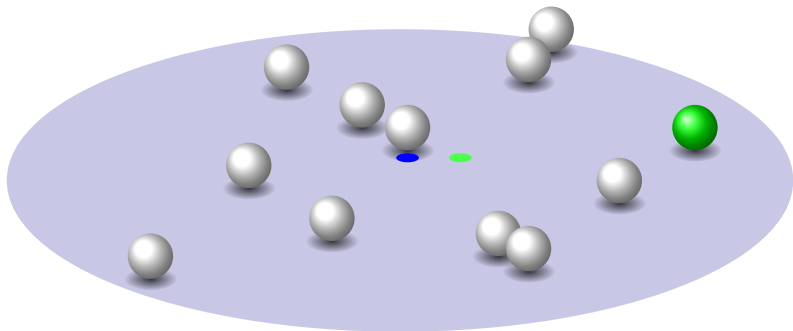
# Pinning a point process

Barycentre



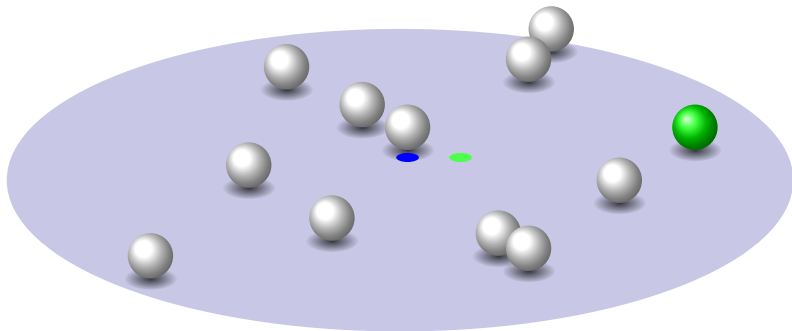
# Pinning a point process

Barycentre



# Pinning a point process

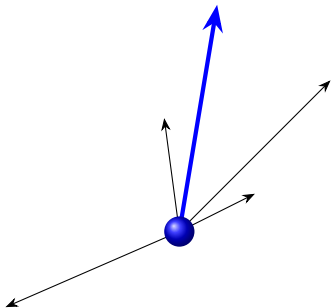
Barycentre



task: modify configuration without disbalancing

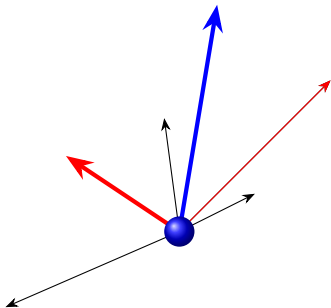
# Pinning a point process

First moment



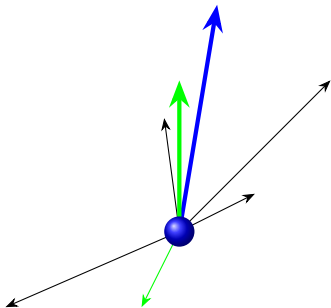
# Pinning a point process

First moment



# Pinning a point process

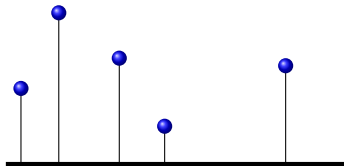
First moment





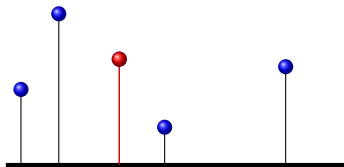
# Pinning a point process

First moment



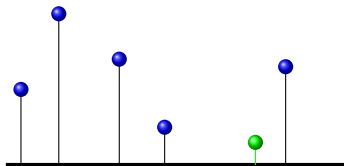
# Pinning a point process

First moment



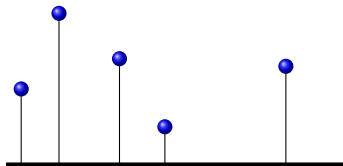
# Pinning a point process

First moment



# Pinning a point process

First moment



task: modify measure without changing total mass

# Application to simulation

## Monte-Carlo simulation

via birth-and-death processes

- ▶ simple
- ▶ functionals  $\mathfrak{b}$  and  $\mathfrak{m}$  not invariant
- ▶  $\{\mathfrak{b} = a\}$  unlikely

Simulation of pinned point configuration

Rejection method more or less unfeasible

# Application to simulation

## Monte-Carlo simulation

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## Simulation of pinned point configuration

Rejection method more or less unfeasible

## Previous Work



G. Conforti, T. Kosenkova, S. Røelly:

Conditioned point processes with application to Lévy bridges  
(2018)

- ▶ large class of Poisson processes and pinning of first moment
- ▶ application to Lévy bridges
- ▶ idea:
  - ▶ **remove** two distinct points and add a suitably chosen one
  - ▶ remove one point and **add** one point together with a suitably chosen one

number of points increases/decreases by one

# Transformations and Invariance

## Transformations of point configurations

for point configuration  $\mu$  and points  $x, y \in \mu$ ,

$$\mu \mapsto \mu - \delta_x - \delta_y + \delta_z$$

## Invariance

functionals  $\mathfrak{b}$  and  $\mathfrak{m}$  shall remain invariant

$$\begin{aligned}\mathfrak{b}(\mu) = \mathfrak{b}(\mu - \delta_x - \delta_y + \delta_z) &\Leftrightarrow z = x + y - \mathfrak{b}\mu; \\ \mathfrak{m}(\mu) = \mathfrak{m}(\mu - \delta_x - \delta_y + \delta_z) &\Leftrightarrow z = x + y.\end{aligned}$$

- ▶ for any two points, the one is determined
- ▶ further functionals?



# State space and conditions

Choose . . .

- ▶ state space
  - ▶  $\mathbb{R}^d$     ▶  $\mathbb{Z}^d$  or any grid
- ▶ pinning of
  - ▶ barycentre  $\mathfrak{b}$     ▶ first moment  $\mathfrak{m}$
- ▶ focus on  $\mathbb{R}^d$  and  $\mathfrak{b}$

# Papangelou processes

Defining equation and examples

## IBPF( $\pi$ )

A point process  $N$  is a Papangelou process if

$$\mathbf{E} \left[ \int h(x, N) N(dx) \right] = \mathbf{E} \left[ \int h(x, N + \delta_x) \pi(N, dx) \right]$$

rate of removal  $N(dx)$ , rate of addition  $\pi(N, dx)$

## Examples

- 1 Poisson process  $\pi(\mu, dx) = \rho(dx)$
- 2 Gibbs process  $\pi(\mu, dx) = \exp(-U(x | \mu)) dx$

# Papangelou processes

## Basic assumptions

### ① Absolute continuity of $\pi$

- ▶ density denoted by  $\pi$
- ▶ rules out some examples with e.g. reinforcement

### ② Compatibility with transformation

- ▶  $\pi^{(2)}(\mu - \delta_z; z - y - \mathfrak{b}\mu, y) > 0$  implies  $\pi(\mu - \delta_z, z) > 0$

# Papangelou processes

## Second-order IBPF

### IBPF-2( $\sigma$ )

Let  $N$  be a solution of IBPF( $\pi$ ), then

$$\begin{aligned} \mathbf{E} \left[ \int h(x, y, N) N^{(2)}(dx, dy) \right] \\ = \mathbf{E} \left[ \int h(x, y, N + \delta_{z-y-b} + \delta_y - \delta_z) \sigma(N, y, z) dy N(dz) \right] \end{aligned}$$

where

$$\sigma(N, y, z) = \frac{\pi^{(2)}(N - \delta_z, z - y - b, y)}{\pi(N - \delta_z, z)}, \quad z \in N.$$

- ▶  $\sigma$  measures preference
- ▶ IBPF-2 is no characterization

# Pinning point processes

## Simple properties

### Pinning and properties

Let  $N$  be a finite point process,  $a \in \mathbb{R}^d$

- ▶  $\mathcal{L}(\mathfrak{b}) =: \tau$ , distribution on  $\mathbb{R}^d \cup \{o\}$  and absolutely continuous on  $\mathbb{R}^d$
- ▶  $N^a$  is  $N$  conditioned on  $\{\mathfrak{b} = a\}$
- ▶  $N^a \neq 0$  a.s. for  $\tau$ -a.e.  $a \in \mathbb{R}^d$

### IBPF-2( $\sigma$ ) for pinned Papangelou processes

If  $N$  satisfies IBPF-2( $\sigma$ ), then  $N^a$  satisfies IBPF-2( $\sigma$ ) for  $\tau$ -a.e.  $a \in \mathbb{R}^d$ .

# Pinning point processes

## Simple properties

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# Pinning point processes

## Characterization

### Characterization

Let  $Q$  be the distribution of some point process  $N$  such that

- 1  $Q$  solves IBPF-2,
- 2  $Q(\mathfrak{b} \neq a) = 0$  for some  $a \in \mathbb{R}$ ,
- 3 kernel  $\pi$  is positive and compatible,

then  $Q$  is the distribution of a pinned Papangelou process.

- simple dynamic leaving  $\mathfrak{b}$  invariant

# Pinning point processes

Key properties and key arguments

## Diminished point process

For point process  $N$ , let  $N^-$  be  $N$  with a uniformly chosen point removed.

- ▶ diminution destroys pinning
- ▶  $\mathcal{L}((N^a)^-) \ll \mathcal{L}(N)$  with density

$$\frac{\pi(\mu, (\mu(X) + 1)a - \mu(X) \cdot \mathfrak{b}(\mu))}{\tau(a)}$$

- ▶  $(\mu(X) + 1)a - \mu(X) \cdot \mathfrak{b}(\mu)$  is location of removed point



# Pinning point processes

Key step

## Recover diminished law

If  $Q$  solves IBPF-2( $\sigma$ ),  $Q$  is pinned to  $a \in \mathbb{R}^d$  and  $\pi$  is positive.  
Then  $Q^- \ll \mathcal{L}(N)$  with density

$$\frac{\pi(\mu, (\mu(X) + 1)a - \mu(X) \cdot \mathfrak{b}(\mu))}{\tau(a)}.$$

## Recover law (CKR)

If  $Q$  is pinned to some  $a \in \mathbb{R}$  and  $Q^- = \mathcal{L}((N^a)^-)$ , then  
 $Q = \mathcal{L}(N^a)$ .

# Pinning point processes

Key step

## Recover diminished law

If  $Q$  solves IBPF-2( $\sigma$ ),  $Q$  is pinned to  $a \in \mathbb{R}^d$  and  $\pi$  is positive. Then  $Q^- \ll \mathcal{L}(N)$  with density

$$\frac{\pi(\mu, (\mu(X) + 1)a - \mu(X) \cdot \mathfrak{b}(\mu))}{\tau(a)}.$$

## Recover law (CKR)

If  $Q$  is pinned to some  $a \in \mathbb{R}$  and  $Q^- = \mathcal{L}((N^a)^-)$ , then  $Q = \mathcal{L}(N^a)$ .

# Further situations

## First moment

### First moment $\mathfrak{m}$

- ▶ state space  $\mathbb{R}^d$  and  $\mathfrak{m}$ 
  - ▶ pinning on  $\mathfrak{m} = a \neq 0$  rules out empty configurations
- ▶ invariance in case of  $z = x + y$
- ▶ assumptions
  - ▶ absolute continuity condition
  - ▶ compatibility condition
- ▶ adjustments in IBPF-2( $\sigma$ )
  - ▶  $z - y + \mathfrak{b}$  replaced by  $z - y$
  - ▶ (also in  $\sigma$ )

# Further situations

## First moment

### First moment $\mathfrak{m}$

- ▶ state space  $\mathbb{Z}^d$  and  $\mathfrak{m}$
- ▶ not allowed in CKR
- ▶ absolute continuity with respect to counting measure
- ▶ adjustment in proof of IBPF-2( $\sigma$ )

# Finally

- ▶ derived IBPF-2 for pinned Papangelou process
- ▶ IBPF-2+pinning characterizes law
- ▶ description of all laws of IBPF-2?